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Testing railway capacity using modern microsimulation programs

Abstract: In a time of dynamic changes in the railway market and nascent need of adjustment the infrastructure to increasing traffic flow and modern rolling stock, the issue of capacity is becoming more and more essential. In this publication the modern attempt at testing capacity – utilization of microsimulation program using as an example a section of the railway with diverse equipment is presented.

Keywords: Microsimulation; RailSys; Railway capacity

Introduction

Increasing the capacity is an important requirement for tenders announced by PKP Polskie Linie Kolejowe S.A. for the modernization of railway lines because in order for the railway to become competitive with other modes of transport it must offer the passenger an attractive offer of long-distance connections as well as within urban agglomerations.

Railway infrastructure, especially in the case of railway hubs, is constantly being designed on the basis of static capacity calculations [8]. This often leads to the fact that the constructed infrastructure does not correspond to the demand for actual traffic load in a regular timetable. Hence the wider use of simulation programs. They allow for the implementation of load adjustments in the anticipated operational plan on the model of the infrastructure being designed, identification of bottlenecks, proposal and checking options for their removal.

Characteristics of parameters affecting the capacity of the railway line

The definition of the capacity of a railway line says that it is the ability to perform on it train journeys within a certain time [18]. It is expressed in the largest number of trains or pairs of trains that can cross a given distance (part, route) of a railway line at a given time, usually, it is a day or morning and an afternoon rush hours.

The throughput capacity depends on:

- railway parameters, such as maximum permitted speed or number and nature of speed limits;
- number of tracks;
- dividing lines into trails;
- type of traffic control devices installed on the network;
- technical characteristics of trains passing through a given network element,
- i.e. type of trains, technical speed, weight and length of trainsets, locomotive traction characteristics, required braking distances;
- difficulties on the railway road, such as closures and repairs.

Too low speed on the Polish rail network is one of the problems most frequently recognized by carriers [33]. The most common reason for speed restrictions is the poor condition of a railway or engineering facility. Too low speed not only extends the driving time but also causes blocking of routes, which significantly affects the reduction of the line's capacity.

Another parameter affecting the capacity of the line is the number of tracks, on two-way sections, it is usually possible to observe up to four times more bandwidth than on single-track routes [27]. However, the second track does not always solve the problem of too low capacity, because the bottlenecks are stations where crossings and passing trains take place.

What is more important is the distance between successive stations, especially on singletrack lines due to the aforementioned possibility of overtaking or passing only at stations. The shorter these intervals, the shorter the travel time of the train.

The type of rail traffic control devices has a significant impact on the capacity of the line. The main task of traffic control devices is to ensure a safe distance between trains. This is accomplished by block spacing. There may be only one train on each of the spaces. Their length is very important because regardless of the position of the train on the stretch, the entire section of the line is considered to be occupied. In the book "Fundamentals of railway traffic control. Functions, requirements, and the outline of the technique "Mirosława Dąbrowy - Bajon [6] compared succession times, bandwidth and speed at 3 ETCS levels. Some assumptions have been made:

- length of block spacing on a straight track for level 1 and 2 of 1500 meters,

- the response time of the RBC control center for level 2 and 3 or the signaling system for level 1, without taking into account the adjustment of the crossover - 5 s,

- train length up to 400 m,

- guaranteed delay value in curbing -0.6 m/s^2 ,

- brake system response time -6 s,

- driver's reaction time -5 s,

- capacity margin of the line -10%.

What was shown with these assumptions is shown in the table below.

ETCS level	train succession	capacity N _{max}	speed v _{max} [km/h]	
	time tn [min]	[poc/h]		
1	3	20	160	
2	2,5	24	300	
3	2	30	500	

	Tab. 1 .	. Comparison	of 3 E	TCS levels	due to	capacity
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Source: own elaboration based on data available in "Podstawy Sterowania Ruchem Kolejowym. Funkcje, wymagania, zarys techniki"

The technical characteristics of trains crossing the line are not insignificant. Mixed traffic, i.e. a situation when trains with different parameters and different categories move along the line adversely affect the capacity of the line. This is mainly due to the need to overtake slower trains by the faster ones. What becomes problematic in the situations is described above. Important train parameters, due to the length of the route occupied, the maximum speed of the rolling stock, its length, acceleration and braking characteristics are.

In addition, any difficulties such as closures, particularly within a station, significantly limit the possibility of cross-train maneuvers and overtaking. What's more, for example in the case of closing side tracks, carriers after finishing the train run are forced to leave trains on the main tracks.

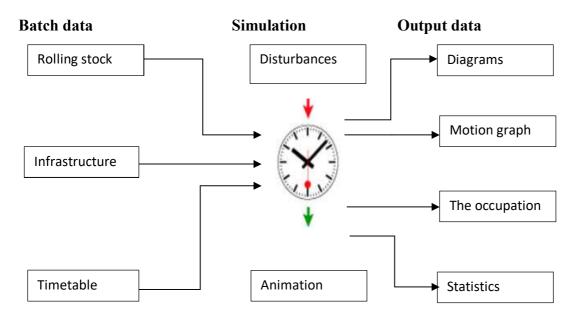
Principle of microsimulation programs operation

The most popular programs used to perform microsymulation are RailSys of the German company RMCon and the Swiss OpenTrack.

Thanks to them, the user can:

- specify infrastructure requirements for the railway network,
- analyze the capacity of the line and station,
- introduce and analyze rolling stock,
- calculate the travel time,
- construct a timetable,
- design various types of signaling,
- analyze the effects of defects in the systems introduced, perform simulation.

The general principle of operation of microsimulation programs used in the design of a railway line is symbolically presented in the following graphics.



1. General scheme of operation of microsimulation programs *Source: own study based on data provided by RMCon and Opentrack*

The infrastructure data entered are, among others, the track system, signaling and all other relevant infrastructure elements (such as line speed, fixed speed limits, guard roads, stop indicators on platforms, block intervals, blockade interlock, etc.).

When the infrastructure is ready, it is possible to start the timetable, but before entering it, enter the data on the rolling stock, i.e. maximum speed, length, weight, number of axles, type of drive, type of rolling stock (locomotive or traction unit), additional the number of seats and standing places can be determined.

Base data	Acc. diagram	Dec. diagram	Rolling resistances	Comments
Traction unit ty	/pe			
Name: EN57				
Data				
Vmax [km/h]:	1	10		
Length [m]:	6	4.970		
Mass [t]:	1	26.500		
Adhesion mass	;[t]: 1	26.500		
Number of axi	es: 1	2		
Traction type:	e	lectric -		
Type:	1	raction unit 👻		
Number of sea	its: C	·		
Amount of sta	nding room: C			

2. Sample data on rolling stock entered into RailSys Source: RailSys

In addition to the basic data, more accurate regarding traction characteristics should be introduced. For each speed an acceleration force is input and on this basis, the program generates a graph.

ase dat	a Acc. di	agram Dec.	diagram Rolling	resistances	Comments
Diagran	n				
from V	/ [km/h]	from V [mph]	from F [kN] to V	[km/h] * [[kN]
	0.000	0.000	102,000		102.000
	1.000	0.621	102.000	2.000	
	2.000	1.243	102,000	3.000	
	3.000	1.864	102.000	4.000	
	4.000	2.485	102.000	5.000	
	5.000	3.107	102,000	6.000	X
	6.000	3.728		7.000	
	7.000	4.350	101.000	8.000	
	8,000	4.971	101.000	9.000	1
	9.000	5.592		10.000	
	10.000	6.214		11.000	
	11.000	6.835	101.000	12.000	17.000
	12.000	7.456	100.000	13.000	
	13.000		2) F171 F1820 F174	14.000	
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	15,000	9.320	99.000	16.000 *	[kn
< N	lew]	Delete		,	7497 99-10 1227
					Mark fix points Whark current section
Ŷ	reate	Smoothing	Qose Q	ptimising	There can be a second
electe	d section				
				V [km/h]	F [kN]
Type	Straight line (f	=a+b*V) ▼	First fix point:	0.000	102.000
			Intermediate fix po	oint: 0.000	0.000
			The module in p	June: Discool	[arose

3. An example graph of the relationship of the force accelerating from the rolling stock generated in the RailSys program *Source: RailSys*

The next step is to determine the course of individual trains. After selecting the rolling stock and route, the timetable is entered, i.e. the time of arrival and departure from individual stations and stop time on them as shown in the figure below:

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vame:	2				✓ Name	21					
a contrat					• Name	-					
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	Station	Station name	Platfm B-1	Line 202	Train route	StopType	Arrival	Depart,	SchDw [s] MinDi		
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3	Da	Damnica	B-1	202	[Jr]-[202/1]-[1]-[55]-[202/1] (1)	No stop			0	9	_
4	55	Strzyzyno Slups	B-1	202	[Da]-[202/1]-[1]-[GP]-[202/1](1)	Scheduled sto	o/Departu	ure not be	fore schedule		
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	ls.	A second second representation of the second	-	200				201 102			/hen passi
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4. Example of setting the train schedule for the train in the RailSys program, taking into account the planned stops, times of arrivals and departures

Source: RailSys

The program automatically generates a traffic graph. On this basis, it detects conflicts resulting from the passage of trains taking into account the routes, block intervals or passing trains at stations. When changing the route, the program instantly recalculates travel times and generates new ones, taking into account the data on the rolling stock and infrastructure, which is why the more accurate the user input is, the more accurate and real-time the timetable will be and it will be easier to locate the so-called bottlenecks and collision venues, and thus proposing changes to improve traffic on the line or stretch.

When the timetable is entered, you can go on to simulate the passage of trains.

Parameters of the tested line segment

In the course of the analyzes, the capacity research covered a section of a railway line more than 100 kilometers long, fully electrified, with a national significance. Only on about 10% of its length is a two-track line, only one track runs on the remaining one. There are different train speeds on the section in question. Differences are also found in the equipment of lines in railway traffic control devices - track and station. Temporary speed limits have been introduced in individual sections. There are 15 stations and 6 passenger stops on the section under development. Only passenger traffic is taken into account. The RailSys program was used for the simulation in version 8.9.92.

Four variants were compared, differing in the elements of infrastructure, train control systems, and permitted speeds, for each of the variants a new track system was introduced, a new timetable was constructed, and a suitable rolling stock adapted. For more reliable results, each of the variants was guided by the same schedule for creating timetables. Trains were divided into 5 groups, differing in routes and stops where they stop, sometimes stationary stations systematized also naming, that is numbers given to them in the timetable, as well as a specific rolling stock assigned to each group.

The trains were introduced while maintaining the rules set out above. The day was divided into hourly intervals. The most sensitive hours are the morning rush hours between 6:00 and 9:00 and the afternoon hours between 15:00 and 18:00. Trains were introduced from approximately 5:00 to 23:00, sometimes midnight.

The main rule in the generation of runs was right-hand traffic, the principle of the smallest crossings is also important, it means running trains that do not stop at the station, if possible, as the simplest route excluding crossings, still maintaining right-hand traffic.

In variant 1, the speed of 140 km / h has been introduced along the entire length, however, the maximum speed cannot be reached anywhere (see Table 2).

In option 2, apart from increasing the speed to 160 km / h, the track system was also changed. On the section about the first 6 kilometers, it was proposed to build 1 track and dynamic junctions (i.e. the second track between the passing stations) on the total length of almost 40 kilometers. However, in this case, too, the desired maximum speed has not been achieved anywhere (see Table 2.).

In variant 3, in addition to increasing the speed to 160 km / h, the track system was also changed. As in the previous scenario, on the six-kilometer section, it was proposed to build 1 track, two on the section of almost 4 kilometers, one on the over forty-kilometer stretch and a dynamic one on the section of 15 kilometers. In this variant, the maximum speed has also not been achieved anywhere (see Table 2).

In option 4, in addition to increasing the speed to 200 km / h, the track system was also changed. As in the previous variants, on the six-kilometer section, it was proposed to build 1 track, two on a twelve-kilometer stretch and one on a more than forty-kilometer stretch and a dynamic passage on a stretch of 15 kilometers. In this variant, the maximum speed has also not been achieved anywhere (see Table 2).

Analysis of the results

As mentioned above, the desired maximum speed has not been achieved on the entire length of the section in question. The specification of the length of individual sections and the maximum speed achieved on them, broken down by variants, is presented in the table below.

	W1		W2		W3	W4	
section	maximum	section	maximum	section	maximum	section	maximum
	speed		speed		speed		speed
[km]	[km/h]	[km]	[km/h]	[km]	[km/h]	[km]	[km/h]
0.340	100	3.488	160	3.500	160	3.500	160
2.930	140	5.843	150	0.330	150	0.330	150
0.570	120	0.502	140	5.510	160	5.530	160
5.600	140	11.495	160	0.510	140	0.510	140
0.200	110	1.154	140	11.490	160	11.470	160
11.690	140	39.779	160	1.100	140	1.100	140
0.580	130	0.643	140	81.040	160	7.110	160
30.640	140	1.138	150	0.450	130	20.880	200
0.895	120	39.468	160	4.645	100	3.620	160
8.845	140	0.453	130			45.680	200
0.610	130	4.612	100			3.680	160
40.62	140					0.460	130
0.430	120					4.705	100
0.410	90						
4.215	80						

Tab. 2. List of maximum speeds for individual variants

Source: own elaboration based on data obtained after entering information into the RailSys program

On the basis of this table it can be seen that only on some sections we managed to achieve the maximum for a given variant speed, on the other it was smaller, it may be due to driving in the reverse direction, turnouts or too short intervals between successive outposts, so the train is not in able to accelerate to the desired speed.

For the comparison of variants, in addition to the timetable introduced, the same rolling stock of the same routes was simulated without stopping, using the mileage characteristic for a given rolling stock. The rolling stock used for comparative analyzes were electric multiple units - EN57 and ED74 as well as the SA138 railbus.

section	variant	V1	V2	V3	V4
[km]	stock		time of trav	el [h:min:s]	
5,68	EN57	0:03:15	0:03:12	0:03:12	0:03:12
	ED74	0:02:34	0:02:24	0:02:23	0:02:25
	SA138	0:03:22	0:03:19	0:03:19	0:03:19
3,69	EN57	0:02:01	0:01:55	0:01:54	0:01:54
	ED74	0:01:36	0:01:24	0:01:25	0:01:25
	SA138	0:02:05	0:01:58	0:01:59	0:01:59
8,46	EN57	0:05:12	0:05:39	0:05:11	0:05:11
	ED74	0:04:02	0:04:14	0:04:13	0:03:47
	SA138				
35,75	EN57	0:20:42	0:20:51	0:20:41	0:20:41
	ED74	0:16:02	0:15:07	0:15:03	0:15:12
	SA138				
51,43	EN57	0:30:15	0:30:15	0:30:09	0:30:09
	ED74	0:23:12	0:21:47	0:21:25	0:21:40
	SA138				

Tab. 3. Comparison of options

Source: own study based on the timetable introduced into the RailSys program

As you can see, not always increasing the speed allowed on the line shortens the travel time. This is due to the fact that in a specific case the route leading by the added track may turn out to be slightly longer. In the case of the study of a single journey time, this may indeed result in a slight increase in travel time, however, when passing several trains it will be easier to pass, especially those from opposite directions because everyone will have their own track and prevent collisions.

It is impossible to draw a specific value from the program about the capacity of the line, therefore to illustrate the impact of the changes introduced in the next variants on the capacity of the lines, as many as possible EN57 trains passing through the entire route without stopping both from one side and the other. The capacity stocks were filled with the largest possible number of trains on sections A and B (in both directions). This has been tested for one hour (10:00 - 11:00). The results obtained are presented in the table below.

Variant		V1	V2	V3	V4
number of train	whole section	2	3	4	4
pairs /h	section A	-	-	1	1
	section B	6	8	2	7

Tab. 4. Comparison of hourly capacity in individual variants

Source: own study based on simulations made in the RailSys program

As you can see, the greatest capacity is provided by the changes proposed in option 4. This shows that the problematic section is over an eight-kilometer section of the single-track line because the addition of an additional track in relation to W3 in W4 significantly increased the capacity. What's more, it showed the necessity of building a long passage at the monorail section from the end of section A. This clearly demonstrates that the key factor in increasing the capacity of the line is not increasing speed, and adding tracks, especially on long sections where trains cannot pass.

Summary

There are many factors that influence the capacity of a line. It is important to analyze the greatest possible number and their mutual influence on each other. Such analyzes carried out using modern tools available on the market, such as microsimulation programs, will facilitate the selection of the most favorable, also from an economic point of view, solution and adjustment to the market needs.

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